Calibration of Heston Local Volatility Models

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Calibration of Heston Local Volatility Models

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- Summary

Model and Stochastic Differential Equations

 Add leverage function *L*(*S_t*, *t*) and mixing factor η to the Heston Model:

$$d \ln S_t = \left(r_t - q_t - \frac{1}{2} L(S_t, t)^2 \nu_t \right) dt + L(S_t, t) \sqrt{\nu_t} dW_t^S$$

$$d\nu_t = \kappa \left(\theta - \nu_t \right) dt + \eta \sigma \sqrt{\nu_t} dW_t^{\nu}$$

$$\rho dt = dW_t^{\nu} dW_t^S$$

• Leverage $L(x_t, t)$ is given by probability density $p(S_t, \nu, t)$ and

$$L(S_t, t) = \frac{\sigma_{LV}(S_t, t)}{\sqrt{\mathbb{E}[\nu_t | S = S_t]}} = \sigma_{LV}(S_t, t) \sqrt{\frac{\int_{\mathbb{R}^+} p(S_t, \nu, t) d\nu}{\int_{\mathbb{R}^+} \nu p(S_t, \nu, t) d\nu}}$$

• Mixing factor η tunes between stochastic and local volatility

Cheat Sheet: Link between SDE and PDE

Starting point is a multidimensional SDE of the form:

$$d\boldsymbol{x}_t = \boldsymbol{\mu}(\boldsymbol{x}_t, t) dt + \boldsymbol{\sigma}(\boldsymbol{x}_t, t) d\boldsymbol{W}_t$$

Feynman-Kac: price of a derivative $u(\mathbf{x}_t, t)$ with boundary condition $u(\mathbf{x}_T, T)$ at maturity *T* is given by:

$$\partial_t u + \sum_{k=1}^n \mu_i \partial_{x_k} u + \frac{1}{2} \sum_{k,l=1}^n \left(\sigma \sigma^T \right)_{kl} \partial_{x_k} \partial_{x_l} u - r u = 0$$

Fokker-Planck: time evolution of the probability density function $p(\mathbf{x}_t, t)$ with the initial condition $p(\mathbf{x}, t = 0) = \delta(\mathbf{x} - \mathbf{x_0})$ is given by:

$$\partial_t \boldsymbol{\rho} = -\sum_{k=1}^n \partial_{x_k} \left[\mu_i \boldsymbol{\rho} \right] + \frac{1}{2} \sum_{k,l=1}^n \partial_{x_k} \partial_{x_l} \left[\left(\boldsymbol{\sigma} \boldsymbol{\sigma}^T \right)_{kl} \boldsymbol{\rho} \right]$$

The SLV model leads to following Feynman-Kac equation for a function $u : \mathbb{R} \times \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \to \mathbb{R}, (x, \nu, t) \mapsto u(x, \nu, t)$:

$$0 = \partial_t u + \frac{1}{2} L^2 \nu \partial_x^2 u + \frac{1}{2} \eta^2 \sigma^2 \nu \partial_\nu^2 u + \eta \sigma \nu \rho L \partial_x \partial_\nu u + \left(r - q - \frac{1}{2} L^2 \nu \right) \partial_x u + \kappa \left(\theta - \nu \right) \partial_\nu u - r u$$

- PDE can be solved using either Implict scheme (slow) or more advanced operator splitting schemes like modified Craig-Sneyd or Hundsdorfer-Verwer in conjunction with damping steps (fast).
- Implementation is mostly harmless, extend FdmHestonOp.

The corresponding Fokker-Planck equation for the probability density $p : \mathbb{R} \times \mathbb{R}_{\geq 0} \times \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}, (x, \nu, t) \mapsto p(x, \nu, t)$ is:

$$\partial_{t} \boldsymbol{\rho} = \frac{1}{2} \partial_{x}^{2} \left[L^{2} \nu \boldsymbol{\rho} \right] + \frac{1}{2} \eta^{2} \sigma^{2} \partial_{\nu}^{2} \left[\nu \boldsymbol{\rho} \right] + \eta \sigma \rho \partial_{x} \partial_{\nu} \left[L \nu \boldsymbol{\rho} \right] \\ - \partial_{x} \left[\left(r - \boldsymbol{q} - \frac{1}{2} L^{2} \nu \right) \boldsymbol{\rho} \right] - \partial_{\nu} \left[\kappa \left(\theta - \nu \right) \boldsymbol{\rho} \right]$$

- Numerical solution of the PDE is cumbersome due to difficult boundary conditions and the Dirac delta distribution as the initial condition.
- PDE can be efficiently solved using operator splitting schemes, preferable the modified Craig-Sneyd scheme

Fokker-Planck Calibration: Last Year's Tool Set

- Coordinate transformation $z = \ln \nu$ to overcome divergent probability density at $\nu \rightarrow 0$
- Proper implementation of zero flux boundary condition for $\nu \rightarrow 0$ and $\nu \rightarrow \nu_{max}$
- Non-uniform meshes in two dimensions
- Semi-Analytical approximation of initial Dirac distribution for small t



• Three important improvements have been added since then

Use Fokker-Planck equation to get from

$$p(x, \nu, t) \rightarrow p(x, \nu, t + \Delta t)$$

assuming a piecewise constant leverage function $L(x_t, t)$ in t

2 Calculate leverage function at $t + \Delta t$:

$$L(x,t+\Delta t) = \sigma_{LV}(x,t+\Delta t) \sqrt{\frac{\int_{\mathbb{R}^+} p(x,\nu,t+\Delta t) d\nu}{\int_{\mathbb{R}^+} \nu p(x,\nu,t+\Delta t) d\nu}}$$

3 Set $t := t + \Delta t$

If t is smaller than the final maturity goto

Fokker-Planck Calibration: Prediction-Correction Step

• Set $L(x, t + \Delta t) = L(x, t)$

2 Use Fokker-Planck equation and $L(x_t, t + \Delta t)$ to evolve

$$p(x, \nu, t) \rightarrow p(x, \nu, t + \Delta t)$$

Solution at $t + \Delta t$:

$$L(x,t+\Delta t) = \sigma_{LV}(x,t+\Delta t) \sqrt{\frac{\int_{\mathbb{R}^+} p(x,\nu,t+\Delta t) d\nu}{\int_{\mathbb{R}^+} \nu p(x,\nu,t+\Delta t) d\nu}}$$

- For number of prediction-correction steps goto
- Set $t := t + \Delta t$
- If t is smaller than the final maturity goto

Fokker-Planck Calibration: Grid Optimization

- Observation: The shape of p(x, v, t) changes rapidly for small t
- Adapt time step size with the evolution of the probability density

$$\Delta t(t) = \Delta t_{min} e^{-\beta t} + \Delta t_{max} (1 - e^{-\beta t})$$

- Adaptive grid boundaries to concentrate the grid at the singularity then spread out with the evolving density
- The local volatility surface can be used as a guide in *x* direction, since it generates the right density
- Distribution in vt direction is known and can be used to set the size.

Grid Optimization: Examples



Calibration of Heston Local Volatility Models

Grid Optimization: Cruise Control

- The Calibration routine ends up with many grid related parameters
- Good news: Quality of the solution can be checked at any time

$$\int_{-\infty}^{\infty} p(x,\nu,t) dx \stackrel{!}{=} \frac{\eta^2 \sigma^2 \left(1 - e^{-\kappa t}\right)}{4\kappa} \chi_d^{\prime 2} \left(\frac{4\kappa e^{-\kappa t}}{\eta^2 \sigma^2 \left(1 - e^{-\kappa t}\right)} \nu_0\right)$$
$$\int_{0}^{\infty} p(x,\nu,t) d\nu \stackrel{!}{=} p_{loc}(x,t)$$

where p_{loc} is the solution of the corresponding Local Volatility Fokker-Planck equation ¹

¹Bad news: We had to implement a Fokker-Planck solver for Local Volatility models

Cruise Control: Feller Constraint Fulfilled



t=0.0041

Cruise Control: Feller Constraint Violated



t=0.0005

- The backward Feyman-Kac equation is much simpler to solve than the Fokker-Planck forward equation
- Boundary condition is more well behaved and the initial start condition is not a Dirac delta distribution.
- Does brute force calibration via the Feynman-Kac equation work?
 - Define leverage function by a two dimensional interpolation on benchmark options
 - Value of the leverage function at each benchmark option is a parameter of the optimisation
 - Could add exotics to that, too ..

Feyman-Kac Calibration: Performance

- The Levenberg-Marquardt optimizer needs the partial derivatives against all parameters for an optimisation step
- Number of option valuations per Levenberg-Marquardt step grows with square of number of benchmark instruments
- Each option valuation translates into solving a two dimensional PDE
- Needs big machines and parallel computing

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		Commit (GB)	35/133		
Kernel Memory (MB)					
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Nonpaged	707	Resource	Monitor		
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Feyman-Kac Calibration: GPU Computing

- Implementing Operator Splitting using recent CUDA tools has become pretty straight forward
- Construct operators on CPU and transfer to GPU via standard sparse matrix format



Feyman-Kac Calibration: Example



Leverage Function calibrated by brute force optimisation on a $7 \otimes 11$ option grid

- Resulting leverage function tends to oscillate
- Levenberg-Marquardt gets stuck in sub-minima
- Even on big machines (e.g. 64 nodes) calibration might take more than 30 minutes.
- Quadratic runtime scaling with number of benchmark instruments does not allow for a fine granular calibration
- The dual equation or AAD might help to mitigate some performance problems
- GPU will not help as PDE usually do not scale properly on GPUs

\implies Feyman-Kac calibration does not look promising

Given a calibrated Heston model and a calibrated local volatility model we can use the SLV model

$$d \ln S_t = \left(r_t - q_t - \frac{1}{2} L(S_t, t)^2 \nu_t \right) dt + L(S_t, t) \sqrt{\nu_t} dW_t^S$$

$$d\nu_t = \kappa \left(\theta - \nu_t \right) dt + \eta \sigma \sqrt{\nu_t} dW_t^{\nu}$$

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for two things:

- Remove calibration errors which the stiffer Heston model exhibits, especially skew for short-dated options
- 2 Match the volatility dynamics of the market. Interpolate between the two models by tuning η between 0 and 1.

From Heston via SLV to Local Volatility and Back

- Heston model: $\kappa = 2.0, \theta = 0.09, \rho = -0.75, \sigma = 0.4, \nu_0 = 0.09$
- Calibrate Local Volatility $\sigma_{loc}(S_t, t)$ to match Heston prices
- Define scaled leverage function

$$L^{s}(S_{t},t) = L(S_{t},t)\sqrt{ heta - e^{-\kappa t}(heta -
u_{0})}$$

• For $\eta = 0$ we get

$$L^{s}(S_{t},t) = \sigma_{loc}(S_{t},t)$$

Can be seen as the most complicated way to calibrate a local volatility surface

From Heston via SLV to Local Volatility and Back



Good news: Finite difference framework is already able to deal with SLV. Implementing a Barrier Option Pricer was literally only 5 lines of code

Modified Heston Solver

Case Study: Delta of Vanilla Option

Vanilla Put Option: 3y maturity, S₀=100, strike=100

Delta of ATM Put Option



Case Study: Barrier Option Prices

DOP Barrier Option: 3y maturity, S₀=100, strike=100



Barrier Option Pricing Local Vol vs SLV

Barrier

Case Study: Delta of Barrier Options

DOP Barrier Option: 3y maturity, S₀=100, strike=100

Barrier Option Δ_{local} vs Δ_{SLV}



Case Study: Express Option





Case Study: Express Option Prices

Express Option: $S_0 = 100$, trigger=100, put strike=50, 3y maturity, coupon = (10%, 20%, 30%)

Express Option NPV_{local} vs NPV_{SLV}



Case Study: Delta an Express Options

Express Option: $S_0 = 100$, trigger=100, put strike=50, 3y maturity, coupon = (10%, 20%, 30%)



Express Option Δ_{Local} vs Δ_{SLV}

Summary: Heston Stochastic Local Volatility

- Adaptive grid sizes speed-up calibration by concentration on important parameter regions
- Prediction-Correction steps have improved the calibration stability significantly
- Use Cruise Control to monitor solution accuracy.
- Calibration via Feynman-Kac backward equation was slow and inaccurate.
- Easy extension of finite difference framework to price Vanilla, Barrier and Express options
- Choice of η can have a significant impact on prices and greeks

Repository: Pull Request #320

https://github.com/jschnetm/quantlib/tree/slv/QuantLib

Literature

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